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Metrics 1

Definition: The **Euclidean distance** between two points $x = (x_1, \dots, x_n) \in \mathbb{R}^n$ and $y = (y_1, \dots, y_n) \in \mathbb{R}^n$ may be computed as

$$d_E(x, y) := \sqrt{(x_1 - y_1)^2 + (x_2 - y_2)^2 + \dots + (x_n - y_n)^2}$$

In practice, straight line distance may not be the most relevant notion of distance. For instance, if you are traveling in a city, you are constrained: you can only walk along the sidewalks, which either go north and south or east and west.

Problem 1: This introduces a more relevant notion of distance between points in \mathbb{R}^2 .

- a) For $x = (x_1, x_2) \in \mathbb{R}^2$ and $y = (y_1, y_2) \in \mathbb{R}^2$, write down a formula for $d_T(x, y)$, the **Taxicab distance** between these two points.

$$d_T(x, y) := \underline{\hspace{15em}}$$

- b) Distance should always be nonnegative. Verify the above definition indeed ensures $d_T(x, y) \geq 0$ for each $x, y \in \mathbb{R}^2$. Find (with proof) a necessary and sufficient condition for when $d_T(x, y) = 0$.

- c) While the analogy of taxicabs breaks down in higher dimensions, for $x = (x_1, \dots, x_n) \in \mathbb{R}^n, y = (y_1, \dots, y_n) \in \mathbb{R}^n$, write down an analogous definition for $d_T(x, y)$. Does it have a similar property as in 1b?

$$d_T(x, y) := \underline{\hspace{15em}}$$

Problem 2: Compute $d_E(x, y)$ and $d_T(x, y)$ for the following points $x, y \in \mathbb{R}^n$ for some n .

- a) $x = (1, 1, 3, 4), y = (-3, 7, -1, 0) \in \mathbb{R}^4$

- b) $x = (-3, 7, -1, 0), y = (1, 1, 3, 4) \in \mathbb{R}^4$

- c) Prove $d_E(x, y) = d_E(y, x)$ and $d_T(x, y) = d_T(y, x)$ for any $x, y \in \mathbb{R}^n$. Our notions of distance are *symmetric*.

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Problem 3:

a) (Optional) Prove by induction the following two *power sum formulas*.

$$\sum_{k=1}^n k = \frac{n^2}{2} + \frac{n}{2}$$

$$\sum_{k=1}^n k^2 = \frac{n^3}{3} + \frac{n^2}{2} + \frac{n}{6}$$

b) Compute and simplify the expressions for $d_E(x, y)$ and $d_T(x, y)$ for $x = (0, \dots, 0), y = (1, 2, 3, \dots, n) \in \mathbb{R}^n$.

c) In part 3b above, which is larger: $d_E(x, y)$ or $d_T(x, y)$? *Hint:* It may help to compare $d_E(x, y)^2$ and $d_T(x, y)^2$ instead.

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Problem 4: Let $x, y \in \mathbb{R}^n$ be two arbitrary points.

a) Which paths between them corresponds to the notion of distance $d_E(x, y)$? Which paths between them correspond to the notion of distance $d_T(x, y)$? It might help to draw a picture.

b) For $n = 1$, show $d_E(x, y) = d_T(x, y)$ for each $x, y \in \mathbb{R}^1$.

c) For $n = 2$, show $d_E(x, y) \leq d_T(x, y)$ for $x = (x_1, x_2), y = (y_1, y_2) \in \mathbb{R}^2$. Find (with proof) necessary and sufficient conditions on x_1, x_2, y_1, y_2 for there to be equality. It may help to refer to your picture in part 4a.

Remark: A similar result (with similar proof) holds for arbitrary n . You can try to prove it in the general case, if you'd like.

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Problem 5: (Taxicab Shapes) The (Euclidean) unit circle can be written as the subset $\{x \in \mathbb{R}^2 : d_E(x, 0) = 1\}$. The (Euclidean) line segment between two points $p, q \in \mathbb{R}^n$ can be written as $\{x \in \mathbb{R}^n : d_E(p, x) + d_E(x, q) = d_E(p, q)\}$.

a) Draw the Taxicab unit circle: $\{x \in \mathbb{R}^2 : d_T(x, 0) = 1\}$.

b) Draw the Taxicab line segment between two points $p, q \in \mathbb{R}^2$: $\{x \in \mathbb{R}^2 : d_T(p, x) + d_T(x, q) = d_T(p, q)\}$.

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Problem 6: While points x, y, z (in order) on a (Euclidean) line segment satisfy $d_E(x, y) + d_E(y, z) = d_E(x, z)$, if y is not on the line segment between x and z , we satisfy the triangle inequality: $d_E(x, z) \leq d_E(x, y) + d_E(y, z)$.

- a) Show $|a + b| \leq |a| + |b|$ for $a, b \in \mathbb{R}$. Use this to conclude the triangle inequality holds for the Euclidean metric in \mathbb{R}^1 . That is, show

$$d_E(x, z) \leq d_E(x, y) + d_E(y, z) \text{ for any } x, y, z \in \mathbb{R}^1$$

(The case for \mathbb{R}^n is harder.)

- b) Show the taxicab metric satisfies $d_T(x, z) \leq d_T(x, y) + d_T(y, z)$ for any $x, y, z \in \mathbb{R}^n$. (Try $n = 1, 2$ first if you are not sure how to start).

Definition: Let X be any nonempty set. A function $d : X \times X \rightarrow \mathbb{R}$ is called a **metric** if

- i) $d(x, y) \geq 0$ for all $x, y \in X$.
- ii) For $x, y \in X$, $d(x, y) = 0$ if and only if $x = y$.
- iii) $d(x, y) = d(y, x)$ for any $x, y \in X$.
- iv) $d(x, z) \leq d(x, y) + d(y, z)$ for any $x, y, z \in X$.

It turns out d_E and d_T both satisfy the definition of a metric on $X = \mathbb{R}^n$. (See 1b, 2c, 6b for the proof that d_T is a metric).